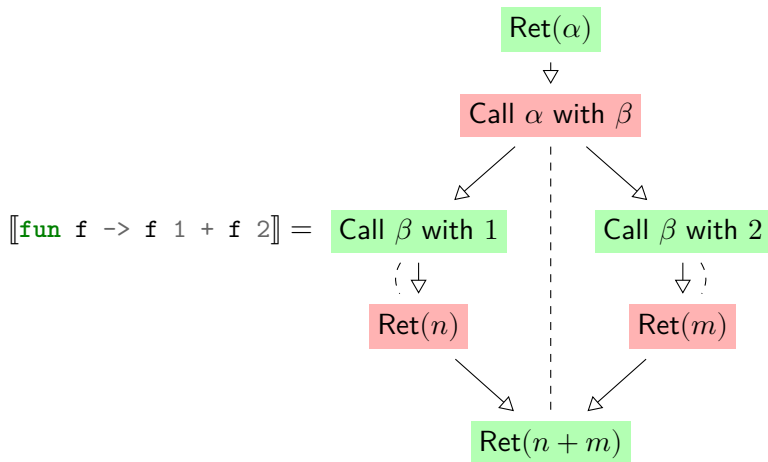


# The Causality Monad

A Monad for Truly-Concurrent Computations

Simon Castellan

# Causal and Interactive Semantics



Programs become:

- ▶ A **set of interaction points** with Context (events)
- ▶ **Causal constraints** between events.

## Interest of such semantics

- ▶ Models strictly more informative than interleaving models
- ▶ In weak memory/distributed systems: focus on causality
- ▶ Reasoning on dependencies (static analysis)

State-of-the art: Concurrent games (initiated by Rideau and Winskel'11). Now:

- ▶ Functional languages
- ▶ Probability
- ▶ Quantum
- ▶ Shared memory
- ▶ Message-passing

**Our goal:** make it “accessible” to define such models.

# How to model a language with concurrent games?

- 1 Model each construct by a strategy.  
E.g. conditional gives rise to a strategy if.
- 2 Use **strategy composition** ( $\odot$ ) to define the interpretation:

$$\llbracket \text{if } M \ N_1 \ N_2 \rrbracket = \text{if} \odot \langle \llbracket M \rrbracket, \llbracket N_1 \rrbracket, \llbracket N_2 \rrbracket \rangle.$$

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Standard denotational approach.

- ✓ Little work involved, heavy lifting done by composition.
- ✓ Reasoning by induction on programs.
- ✓ Compositionality **by design**

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Standard denotational approach.

- ✓ Little work involved, heavy lifting done by composition.
- ✓ Reasoning by induction on programs.
- ✓ Compositionality **by design**

However:

- ✗ Composition operator difficult to understand and untractable.
- ✗ Need to know what a strategy is.
- ✗ Methodology inefficient.

**Goal:** simplify description and implementation of such semantics.

## When to be compositional, and when not to

When computing  $\llbracket P \rrbracket$ , we can take shortcuts:

$$\llbracket \text{if true } M N \rrbracket = \llbracket M \rrbracket \quad \leftarrow \llbracket N \rrbracket \text{ not necessary}$$

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When computing  $\llbracket P \rrbracket$ , we can take shortcuts:

$$\llbracket \text{if true } M N \rrbracket = \llbracket M \rrbracket \quad \leftarrow \llbracket N \rrbracket \text{ not necessary}$$

**Requirement:** compute  $\llbracket \cdot \rrbracket$  somewhat lazily:



## Theorem (Compositionality)

$$\text{project}(t \text{ op } u) = \text{project}(t) \llbracket \text{op} \rrbracket \text{project}(u).$$

**Issue 1 (semantic):** Implicit representation for causal models?



# How semantic interpreters work

A typical semantic interpreter for an imperative language:

```
val interpret : program -> (state -> state)
```

```
let rec interpret program state = match program with  
| Assign (var, value) ->  
  assign var (eval state value) state  
| Seq (t, u) ->  
  let state' = interpret t state in  
  interpret u state'
```

↪ We would like the same style, but with concurrency.

# Monadic interpreters

Such semantic interpreters are **monadic**:

```
type 'a m = state -> 'a * state
val assign : string -> int -> unit m
val eval : expression -> int m
```

```
val interpret : program -> unit m
let rec interpret = function
| Assign (var, value) ->
  let* n = eval value in
  assign var n
| Seq (t, u) ->
  let* () = interpret t in
  interpret u
```

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```

This uses a generalised `let*` on monadic computations:

```
val ( let* ) : 'a m -> ('a -> 'b m) -> 'b m
let ( let* ) m f = fun state ->
  let (v, state') = m state in
  f v state'
```

**Issue 2 (syntactic):** Monadic operations for concurrency?

# Plan

- 1 A monad signature to describe concurrent computations
- 2 An implementation of it inspired by **closure operators**
- 3 A projection to event structures (implicit or explicit).
- 4 Causal interpreter of MiniOCaml.

# I. MONADIC OPERATIONS FOR CONCURRENCY

# Concurrency primitives

Most concurrency primitives mix causality and conflict:

- ▶ Shared memory, Channels à la CCS or  $\pi$ , ...

↪ Difficult to use to describe precisely a causal model.

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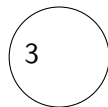
- ▶ Shared memory, Channels à la CCS or  $\pi$ , ...

↪ Difficult to use to describe precisely a causal model. Our recipe:

- ▶ Parallelism (independent subcomputations)
- ▶ Deterministic communication between independent subcomputations
- ▶ Nondeterminism as “incompatibility” between computations.

# The mental model

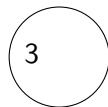
Soup of independent threads:





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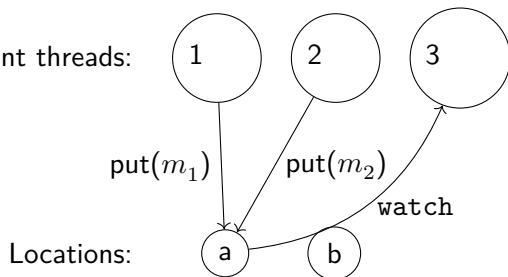


Locations:



# The mental model

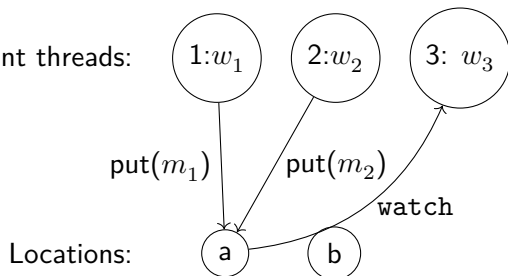
Soup of independent threads:



**Determinism:** Messages **never** consumed, only observed.

# The mental model

Soup of independent threads:



**Determinism:** Messages **never** consumed, only observed.

**Compatibility:** each  $w_i \in \text{World}$ :

- ▶ 3 sees  $m_1$  iff  $w_1 \vee w_3$  is defined,
- ▶ 3 sees  $m_2$  iff  $w_2 \vee w_3$  is defined.

$(\text{World}, \vee)$  must be a partial monoid, eg.

$$\text{World} = (\mathbb{N} \rightarrow \mathbb{N}, \cup).$$

# Monadic operations

```
(* Type of computation returning values of type ['a] *)
```

```
type 'a t
```

```
val return : 'a -> 'a t
```

```
val bind : 'a t -> ('a -> 'b t) -> 'b t
```

```
(* Parallelism *)
```

```
val parallel : 'a t list -> 'a t
```

```
(* Communication *)
```

```
type 'a loc (* morally simply an ID. *)
```

```
val create : unit -> 'a loc
```

```
val put : 'a loc -> 'a -> 'b t (* Never returns *)
```

```
val watch : 'a loc -> 'a t
```

```
(* Nondeterminism: basically a state monad over world *)
```

```
type world = ..
```

```
(* must implement: val join : world -> world -> world option *)
```

```
val world_get : world t
```

```
val world_set : world -> unit t
```

## Examples: determinism

```
(* To run a computation and get the final values *)  
val results : 'a t -> 'a list  
  
# results (return 1)  
- int list = [1]  
# results (parallel [return 1; return 2])  
- int list = [2]  
# results (bind (parallel [return 1; return 2])  
             (fun n -> return (n+1)))  
- int list = [2; 3]
```

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let loc = create ()  
# results (parallel [watch a; put a 1])
```

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```
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- int list = [2; 3]
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```

```
- int list = [1]
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```
# results (parallel [watch a; watch a; put a 1; put a 2])
```

```
- int list = [1; 2; 1; 2]
```

```
# results (watch a)
```

```
- int list = []
```

## Examples: nondeterminism

```
type world = bool option
let join b b' = match (b, b') with
| (None, x) | (x, None) -> x
| Some b, Some b' when b = b' -> Some b
| _ -> None

let coin = parallel [set_world (Some true) >> return true;
                    set_world (Some false) >> return false]
let fork = parallel [return true; return false]
let loc = create ()

# results (fork >>= if b then watch loc else put loc 1)

# results (coin >>= if b then watch loc else put loc 1)
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let loc = create ()

# results (fork >>= if b then watch loc else put loc 1)
- int list = [1]
# results (coin >>= if b then watch loc else put loc 1)
- int list = []
(* Because true and false are returned in incompatible world.
   watch and put are invisible to each other. *)
```

## Expressivity

Signature expressive enough for concurrent data structures.

```
let c = Cell.create 0 (* Create a concurrent memory cell *)
# results (parallel [Cell.set c 1 >> discard;
                    Cell.set c 2 >> discard;
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One result per causal explanation of the read

- 1 0: read is performed first
- 2 First 1: read is performed only after `Cell.set c 1`
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In this case, a world is a trace  $t$  of memory operations on  $c$ :

$t \vee t' =$  maximum of  $t$  and  $t'$  for prefix ordering if defined

$\rightsquigarrow$  Implementation somewhat subtle but short ( $\sim$  20lines)

## II. IMPLEMENTATION OF THE SIGNATURE

# The mental model

Threads are modelled by **state transformers** on:

State :=  $\mathcal{P}(\text{Msg})$      where  $\text{Msg} := \text{Loc} \times \text{Value} \times \text{World}$ .

(Closed) programs are functions  $f : \text{State} \rightarrow \text{State}$  such that:

- ▶ **monotonic**:  $X \subseteq Y \Rightarrow f(X) \subseteq f(Y)$
- ▶ **increasing**:  $X \subseteq f(X)$ .

The **final state** of such an  $f$  is the limit of:

$$\emptyset \subseteq f(\emptyset) \subseteq \dots$$

Two possibilities:

- ▶ **Mathematic world**: limit always exists but may only be reached after a transfinite number of steps.
- ▶ **Real world**: if the sequence does not converge in finite time, final state is not defined.



## The monad in maths

We thus define:

$$T(X) := \text{Loc}(X) \rightarrow \text{World} \rightarrow (\text{State} \rightarrow \text{State})$$

where  $\text{Loc}(X)$  set of locations of type  $X$ .

$$\text{return}(x) := \lambda \ell. \lambda w. \lambda \sigma. \sigma \cup \{(\ell, x, w)\}.$$

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$$\text{bind}(m, f) := \lambda \ell. \lambda w. \lambda \sigma. \text{newloc } \alpha \text{ in}$$

$$\text{parallel}[m \alpha w \sigma; \bigcup_{\substack{(\alpha, v, w_2) \in \sigma \\ w_1 \vee w_2 = w}} f v w \sigma]$$

# The monad in code

State transformers are very inefficient to iterate.

↪ Alternative representation:

$$\mathcal{C} ::= \text{State} \times \mathcal{P}(\text{Loc} \times (\text{Msg} \rightarrow \mathcal{C}))$$

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↪ Fixpoint reached through a transition system avoiding recalculations.



# What is swept under the rug

- 1 How to send the same value twice?  
↪ Pseudo-Nominal solutions
- 2 Handling of public/private names to get a well-behaved equivalence.  
↪ Nominal techniques.
- 3 Choices of data structure to represent State,  $\mathcal{C}$
- 4 Bind is costly (allocation of a name) + parallel  
↪ Free monads to eliminate binds.

### III. GENERATING EVENT STRUCTURES

# The event structure spanned by a state

From a term  $t : T(X)$ , we can extract a final state:

$$\text{final}(t) = \text{lfix}(t \alpha \perp)(\alpha \text{ fresh}).$$

This final state is a *soup of messages*.

To recover some structure, we extend worlds with a *causal view*

$$\text{World} = \{\text{view} : \mathcal{P}(\text{Msg}); \dots\}$$

Then, on  $\sigma \in \text{State}$ , we define:

- ▶ A **partial order**:  $m \leq_{\sigma} m'$  iff  $m \in m'.\text{world.view}$ .
- ▶ A **conflict relation**:  $m \#_{\sigma} m'$  iff  $(m.\text{world} \vee m'.\text{world}) \text{ undef}$ .

This creates an **event structure**.

↪ In general, only consider certain locations.

# Writing an interpreter using Causality

## IV. SEMANTICS OF MINI-OCAML

# Illustration: Semantics of a functional language

## Source:

- ▶ **MiniOCaml**: OCaml restricted to basic datatypes, functions.
- ▶ **Concurrent semantics**: eg.  $(M, N)$

## Target: Causal and Interactive semantics

- ▶ Final Object: Event Structure
- ▶ Event are messages between program and its context
- ▶ Two kinds of events: Call and Returns
- ▶ All messages are “first-order”: functions are passed by name

Protocol described by game semantics. (GS is model-agnostic)

## Two steps

- 1 Monadic translation of the language using Causality.

```
type value = Int of int | Function of (value -> value t)
```

```
let rec eval : expression -> value t = function  
| AstInt n -> return (Int n)  
| AstApp (t, u) -> eval t >>= function  
| Function f -> eval u >>= f
```

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- 2 Game Semantics is used to describe the communication protocol between a program and the context.

```
type msg = {  
  polarity: Program | Context;  
  kind: Call | Return;  
  value: Int of int | Function;  
  ...  
}  
val recv : msg location -> value t  
val send : msg location -> value -> unit t
```



## Combining the two steps

We thus get:

```
val sem : expression -> msg location -> unit t
```

This allows interacting with an expression through a location:

- ▶ Exploring (partially) the behaviour of the program.  
     $\rightsquigarrow$  Replicate certain races hard to simulate.
- ▶ Causal debugging.
- ▶ Dynamic analysis.

# Demo

# Conclusion

## Main contributions:

- ▶ Framework for operational description of causal semantics

Useful for: weak memory, distributed systems, ...

## Perspectives:

- ▶ **Reasoning:** Lots of difficulties (eg. nominal aspects)
- ▶ **Formalisation:** Could be easier than usual causal models on a proof assistant.
- ▶ **Real case study:** Weak memory?
- ▶ **Static analysis:** eg. write abstract interpreters
- ▶ **Finitary infinity:** how to generate Petri Nets?  
*(\* Generates a syntactic loop (à la Petri nets) \*)*  
`val fix : ('a t -> 'a t) -> 'a t`
- ▶ and many other things.